

# Self-stabilizing Minimal Dominating Set Algorithms of Distributed Systems & the Signed Star Domination Number of Cayley Graphs

Well Yu-Chieh Chiu (邱鈺傑)

Department of Applied Mathematics  
National Chiao Tung University  
Hsinchu, Taiwan

August 3, 2014



# Outline

## 1 Introduction

- Basic graph definitions in domination
- Self-stabilization algorithms of distributed systems

## 2 Self-stabilizing MDS algorithms & the stableness

- A  $(4n - 2)$ -move self-stabilizing MDS algorithms
- Four levels of stableness
- Developing an SS MDS-silent algorithm in the distance-2 model

## 3 The signed star domination number of Cayley graphs

- Introduction to signed star domination
- The signed star domination number of the Cayley graphs



# Basic graph definitions

- Distributed systems  $\rightarrow$  graphs
  - $G = (V, E)$  is simple, undirected, finite, and connected.
  - processes  $\rightarrow V, n = |V|$
  - interconnections  $\rightarrow E, m = |E|$
- Notations:
  - $u \sim v$ :  $u$  and  $v$  are adjacent.
  - $\deg(v)$ : degree of  $v$ .
  - $N(v), N[v]$ : (closed) neighborhood of  $v$ .
  - $d(u, v)$ : distance from  $u$  to  $v$ .
  - $G[S]$ : subgraph of  $G$  induced by  $S$ .
  - $u$  is a  $k$ -neighbor of  $v$  if  $d(u, v) = k$ .
  - $N_k(v)$ :  $k$ -neighborhood of  $v$ .



# Domination & Independence

- DS: dominating set.
- MDS: minimal dominating set.
- CDS: connected dominating set.
- IS: independent set.
- MIS: maximal independent set.
- (well known) An MIS of  $G$  is an MDS of  $G$ .



# MDS prob

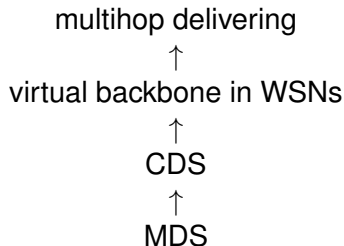
For a distributed system  $G$ , the *minimal dominating set problem* (**MDS prob**) is

- For each node  $v \in V$ , its neighbors are given as input.
- Each node  $v \in V$  decides its decision  $d_v$  as output.
- The set  $S = \{v \in V : d_v = 1\}$  must be an MDS.



# Applications

## Messages routing in wireless sensor networks (WSNs)



# Distributed algo

A distributed algo is:

- Executed independently on each node.
- Defined by a collection of **rules**.
  - Rule: **if precondition then action**;
  - A rule is **enabled** if precondition evaluates true.
  - A node is **privileged** if one of rules is enabled.
- Execution of a rule (taking action) is called a **move**.

## Example

Two simple rules that maintain an MIS  $I$ :

R1: **if**  $v \notin I$  having no neighbor in  $I$  **then**  $v$  joins  $I$ ;

R2: **if**  $v \in I$  having a neighbor in  $I$  **then**  $v$  leaves  $I$ ;



# Definition of Self-stabilization (SS)

## Definition

An algo on a distributed system is called *self-stabilizing* (SS) if the following two properties hold:

- Starting from any illegitimate state, the distributed system reaches a legitimate state in a finite time without any external intervention.
- After convergence, the system remains in the set of legitimate state.

## Example

The previous example (2 simple rules) is SS w.r.t. MIS.





# SS models

Execution models (daemons, schedulers):

- *Central*: choose only one
- *Synchronous*: choose all
- *Distributed*: choose arbitrary subset (practical)

*Deterministic uniform* SS algo assuming synchronous or *distributed daemons* are impossible for an *anonymous system* because the difficulty encountered in **symmetry breaking**.



Our algo. use an **distributed** daemon.

We assume each node  $v$  has  $v.id$ .



# SS graph algo

For finding a vertex subset (such as MIS/MDS prob), we define:

- The states of nodes are categorized into two types:
  - **IN**: If the node is considered in the set  $S$  with the desired property
  - **OUT**: If the node is considered not in  $S$  with the desired property
- **Membership move**: A move s.t. the state of the node changes from **IN** to **OUT** or from **OUT** to **IN** after the execution.



We use terms: **IN nodes**, **OUT nodes**, **IN neighbors**, etc.



## Previous SS MDS algo

	stabilization time	daemon type
Hedetniemi et al. (2003)	$(2n + 1)n$ moves	central
Xu et al. (2003)	$4n$ rounds	synchronous
Turau (2007)	$9n$ moves	distributed
Goddard et al. (2008)	$5n$ moves	distributed

### Main result

We present  $Well_{4n}$ , a  $(4n - 2)$ -move SS MDS algo.



# Well4n

In Well4n every node has state in 4 different values:

- IN (in the set),
- OUT1 (not in the MDS, having a unique IN neighbor),
- OUT2 (not in the MDS, having  $\geq 1$  IN neighbors),
- WAIT (not in the MDS, having no IN neighbor).

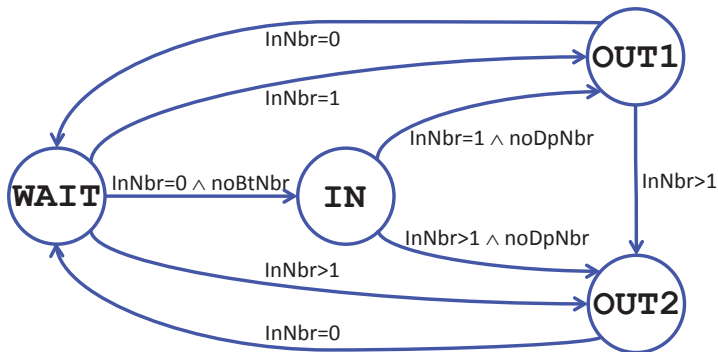
## Definition

In Well4n a configuration is **legitimate** if the set of IN nodes form an MDS and for every OUT node, the state and the number of IN neighbors are consistent.

Notice that a legitimate configuration will not contain any WAIT node



# State diagram of Well4n



# Correctness & convergence

## Theorem

*The proposed algorithm  $Well_{4n}$  is self-stabilizing under an unfair distributed daemon and it stabilizes after at most  $4n - 2$  moves with a minimal dominating set, where  $n$  is the number of nodes. Moreover, the bound  $4n - 2$  is tight.*



# Main result

- MDS-silent: [Turau, 2007] initialized with an MDS does not make any moves.
- MDS-covered: [Hedetniemi et al., 2003] can potentially produce any MDS.
- MDS-stable: (this thesis) not make any membership move when the system is initialized with an MDS.

Level	Feature	SS Algo
$S_1$ -stable	MDS	Turau3n
$S_2$ -stable	MDS-covered	Turau9n, Goddard5n, Well14n
$S_3$ -stable	<b>MDS-stable</b>	?
$S_4$ -stable	MDS-silent	<b>none</b>



# MDS-silent: non-existence

## Theorem

*There exists no SS MDS-silent algo in the normal model.*

## Corollary

*A SS MDS-covered algo in the normal model cannot have only one Boolean variable as its state variable.*

## Conjecture

*There exists **no** SS MDS-stable algo in the normal model.*





# Four levels of stableness

- MDS-covered  $\Rightarrow$  MDS: by definition.
- MDS-stable  $\Rightarrow$  MDS-covered: initialized with any MDS, then system stabilizes with the same MDS.
- MDS-silent  $\Rightarrow$  MDS-stable: membership moves are moves. □

## Theorem

*$S_{i+1}$ -stableness implies  $S_i$ -stableness, for  $i \in \{1, 2, 3\}$ .*



# Four levels of stableness

## Stableness of SS DS algo

Reference	Output	Stableness	Required topology	Anonymous	Daemon	Model	Complexity
Hedetniemi et al. 2003-1	DS	$S_1$	Arbitrary	Yes	Central	Normal	$\leq n - 1$ moves
Hedetniemi et al. 2003-2	MDS	$S_2$	Arbitrary	Yes	Central	Normal	$\leq (2n + 1)n$ moves
Xu et al. 2003	MDS	$S_2$	Arbitrary	No	Synchronous	Normal	$\leq 4n$ rounds
Goddard et al. 2003,2005	MTDS	$S_2$	Arbitrary	No	Central	Normal	$\leq 2^n$ moves
Tarau 2007	MDS	$S_2$	Arbitrary	No	Distributed	Normal	$\leq 9n$ moves
Goddard et al. 2008	MDS	$S_2$	Arbitrary	No	Distributed	Normal	$\leq 5n$ moves
Kamei et al. 2003-1	MkDS	$S_1$	Tree	Yes	Central	Normal	$\leq n^2$ moves
Kamei et al. 2003-2	MkDS	$S_1$	Tree	No	Distributed	Normal	$\leq 3(n - 1)^2$ moves
Huang et al. 2008	M2DS	$S_1$	Arbitrary	Yes	Central	Normal	$\leq 10n + 1$ moves
Kamei et al. 2005	MkDS	$S_1$	Arbitrary	No	Synchronous	Normal	$\leq n$ rounds
Huang et al. 2007	M2DS	$S_1$	Arbitrary	No	Distributed	Normal	
Gairing et al. 2004	MDS	$S_4$	Arbitrary	Yes	Central	Dist-2	$\leq 2n$ moves
Tarau et al. 2012	MkDS	$S_4$	Arbitrary	Yes	Central	Dist-2	$\leq 2n$ moves
Belhoual et al. 2014	MTDS	$S_4$	Arbitrary	Yes	Central	Dist-2	$\leq 2n$ moves
Sec.3.2 in this thesis	MDS	$S_2$	Arbitrary	No	Distributed	Normal	$\leq 4n - 2$ moves
Sec.5.3 in this thesis	MDS	$S_4$	Arbitrary	No	Distributed	Dist-2	$\leq 2n - 1$ moves



# Distance-2 model

## Definition

A distributed system is in the *distance-2 model* if a node can instantaneously see the states of all nodes within distance two from it.

In the literatures, two *transformers* from distance-2 model to normal model are given.

Reference	Slowdown factor	Memory overhead
[Gairing et al. 2004]	$\times O(n^2 m)$	$\times \Omega(\Delta \log n)$
[Turau 2012]	$\times O(m)$	$+ O(\log n)$

The transformed algorithms are **not MDS-silent**.



# Implementing the distance-2 model

We implement the distance-2 model on WSNs by using the *beacon messages*.

Each sensor node:

- 1 Broadcast beacon message periodically.
- 2 Construct/update *neighbor list*.
- 3 Broadcast beacon message with neighbor list.
- 4 After receiving neighbor lists from all neighboring nodes.
  - Construct/update *2-neighbor list* by received neighbor lists.
  - If one rule is enabled, take action.
  - Go back to step 1.



# Correctness and convergence

## Rules of *We112n*

**S1:** if  $v.state = \text{OUT} \wedge \text{noInNbr}(v) \wedge \text{noBtNbr}_2(v)$   
 then  $v.state := \text{IN};$  // enter S

**S2:** if  $v.state = \text{IN} \wedge \neg \text{noInNbr}(v) \wedge \text{noDpNbr}_2(v)$   
 then  $v.state := \text{OUT};$  // leave S

## Theorem

Algorithm *We112n* is self-stabilizing and **MDS-silent** under an unfair distributed daemon in the **distance-2 model**. It stabilizes after at most  $2n - 1$  moves with a minimal dominating set, where  $n$  is the number of nodes.



# The signed star domination: definitions

- A function  $f : E(G) \rightarrow \{-1, 1\}$  is called a **signed star dominating function** (SSDF) on  $G$  if  $\sum_{e \in E_G(v)} f(e) \geq 1$  for every  $v \in V(G)$ , where  $E_G(v)$  is the set of all edges incident to  $v$ .
- The **signed star domination number** of  $G$  is defined as  $\gamma_{SS}(G) = \min\{\sum_{e \in E(G)} f(e) \mid f \text{ is an SSDF on } G\}$ .
- [Xu 2005]
  - Initiated the study of  $\gamma_{SS}$  of graphs
  - $\lceil \frac{n}{2} \rceil \leq \gamma_{SS}(G) \leq 2n - 4$
- [Atapour et al. 2010]
  - $\gamma_{SS}(K_n), \forall n$ 
    - 1-factorable
    - H-factorable



# Cayley graphs

- $\text{Cay}(\Gamma, \Omega)$ : Cayley graph
  - $\Gamma$ : a finite nontrivial group
  - $\Omega$ : a symmetric generating subset of nonidentity elements of  $\Gamma$
- arrange the elements of  $\Omega$  in the form:
   
 $\{\sigma_1, \sigma_2, \dots, \sigma_{2s}, \tau_1, \tau_2, \dots, \tau_t\}$  satisfying
   
 $\sigma_i^{-1} = \sigma_{i+s}, 1 \leq i \leq s$  and  $\tau_j^{-1} = \tau_j, 1 \leq j \leq t$ .
  - $s$  2-factors
  - $t$  1-factors

$$E(G) = \left( \bigcup_{i=1}^s C_i \right) \cup \left( \bigcup_{j=1}^t M_j \right).$$



# Signed star domination of the Cayley graphs

## Lemma

Let  $G$  be an  $r$ -regular graph.

Then we have

$$\gamma_{ss}(G) \geq \begin{cases} \frac{n}{2} & \text{if } r \text{ is odd,} \\ n & \text{if } r \text{ is even,} \\ n + 1 & \text{if } r \text{ is a multiple of 4 and } n \text{ is odd.} \end{cases}$$

## Theorem

Let  $\Gamma$  be a finite group of even order  $n$ , and let  $\Omega$  be a symmetric generating set of  $\Gamma$ . If  $|\Omega|$  is odd, then

$$\gamma_{ss}(\text{Cay}(\Gamma, \Omega)) = \frac{n}{2}.$$



# Signed star domination of the Cayley graphs

## Theorem

*Let  $\Gamma$  be a finite group of order  $n$ , and let  $\Omega$  be a symmetric generating set of  $\Gamma$  with even  $|\Omega|$ . If  $\Omega$  has an odd number of distinct  $\{\sigma, \sigma^{-1}\}$  pairs, or contains an element of even order, then*

$$\gamma_{SS}(\text{Cay}(\Gamma, \Omega)) = n.$$

## Theorem

*Let  $\Gamma$  be a finite cyclic group of odd order  $n$ . Assume that  $\Omega$  is a symmetric subset containing a generator of  $\Gamma$ . If  $|\Omega|$  is a multiple of 4, then*

$$\gamma_{SS}(\text{Cay}(\Gamma, \Omega)) = n + 1.$$

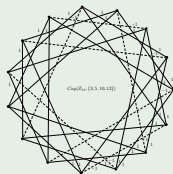
# Signed star domination of the Cayley graphs

## Example

$$\mathbb{Z}_{15} = \{0, 1, \dots, 14\},$$

$$\Omega = \{3, 5, 10, 12\},$$

$$\gamma_{SS}(\text{Cay}(\mathbb{Z}_{15}, \Omega)) = 16$$



## Conjecture

Let  $\Gamma$  be a finite group of order  $n$ , and let  $\Omega = \{\sigma_1, \sigma_2, \dots, \sigma_{2s}\}$  be a symmetric generating set of  $\Gamma$ . If  $s$  is even and no element of  $\Omega$  is of even order, then  $\gamma_{SS}(\text{Cay}(\Gamma, \Omega)) = \begin{cases} n & \text{if } n \text{ is even,} \\ n + 1 & \text{if } n \text{ is odd.} \end{cases}$

# Summary

## ● Main results

- Provide a  $(4n - 2)$ -move SS MDS-covered algo in normal model; bound is tight
- Prove an MDS-silent algo in normal model is impossible
- Develop an SS MDS-silent algo in dist-2 model
- Give partial results on  $\gamma_{SS}$  of Cayley graphs

## ● Future works

- Design an SS MDS-covered algo in normal model using fewer than  $4n - 2$  moves.
- Prove an MDS-stable algo in normal model is impossible
- Multi-self-stabilization
- Complete the results on  $\gamma_{SS}$  of Cayley graphs



謝謝！

Thank you for your attention!

